# 9. Curves, Tangents, Velocity, and Acceleration

In this lecture, we will discuss

- World of Curves
  - Selected examples of curves in 2D and 3D
  - Some examples of paramatrizing a curve
- Tangents, Velocity, and Acceleration

# World of Curves

# Selected examples of curves in 2D and 3D

Recall that a path is a vector-valued function of one variable, and its image, visualized as a geometric object, is a curve.

Below are some examples of curves in 2D with their equations.

Name	Curve	Parametric Equation
Deltoid		$\langle rac{2\cos(t)}{3} + rac{1}{3}\cos(2t) - rac{1}{4}, rac{2\sin(t)}{3} - rac{1}{3}\sin(2t) angle$ , $t\in[0,2\pi]$
Astroid		$\langle \cos^3(t), \sin^3(t)  angle, t \in [0, 2\pi]$
Lemniscate		$\langle rac{\cos(t)}{\sin^2(t)+1}, rac{\sin(t)\cos(t)}{\sin^2(t)+1}  angle, t\in [0,2\pi]$
Heart		$\langle rac{4\sin^3(t)}{5}, rac{1}{20}(13\cos(t)-5\cos(2t)-2\cos(3t)-\cos(4t)) angle, t\in [0,2\pi]$
Lissajous		$\langle \cos(3t)), \sin(5t)  angle$ , $t \in [0, 2\pi]$

Name	Curve	Parametric Equation
Helix		$\langle 2\cos(t),2\sin(t),rac{t}{10} angle$ , $t\in[0,10]$
Spiral on a sphere.		$\langle \cos(t)\cos(18t),\sin(18t)\cos(t),\sin(t) angle$ , $t\in[0,2\pi]$
Torus knot		$\langle \cos(7t)(\cos(8t)+3),\sin(7t)(\cos(8t)+3),\sin(8t) angle, t\in [0,2\pi]$
Spiral in 3D		$\langle t\cos(t),t\sin(t),\ln(t) angle$ , $t\in[0,10\pi]$

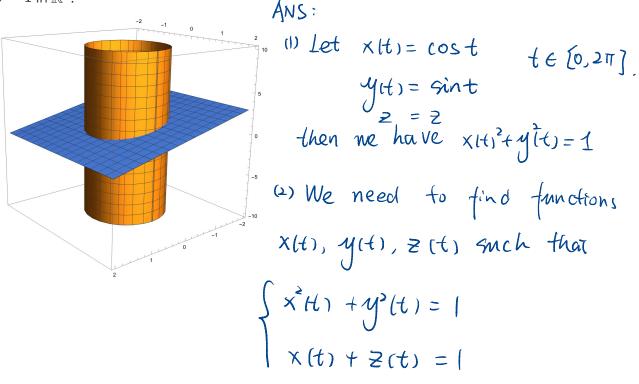
Here are some examples of curves in 3D with their equations.

#### Some examples of paramatrizing a curve

# **Example 1**

(1) (a) Find a vector-parametric equation  $\vec{r}_1(t) = \langle x(t), y(t), z(t) \rangle$  for the shadow of the circular cylinder  $x^2 + y^2 = 1$  in the xy-plane.

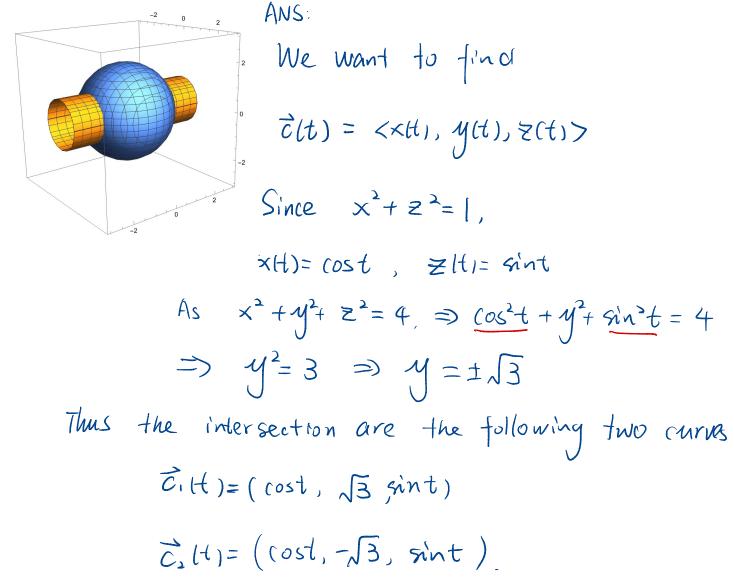
(2) Find a vector-parametric equation for intersection of the circular cylinder  $x^2 + y^2 = 1$  and the plane x + z = 1 in  $\mathbb{R}^3$ .



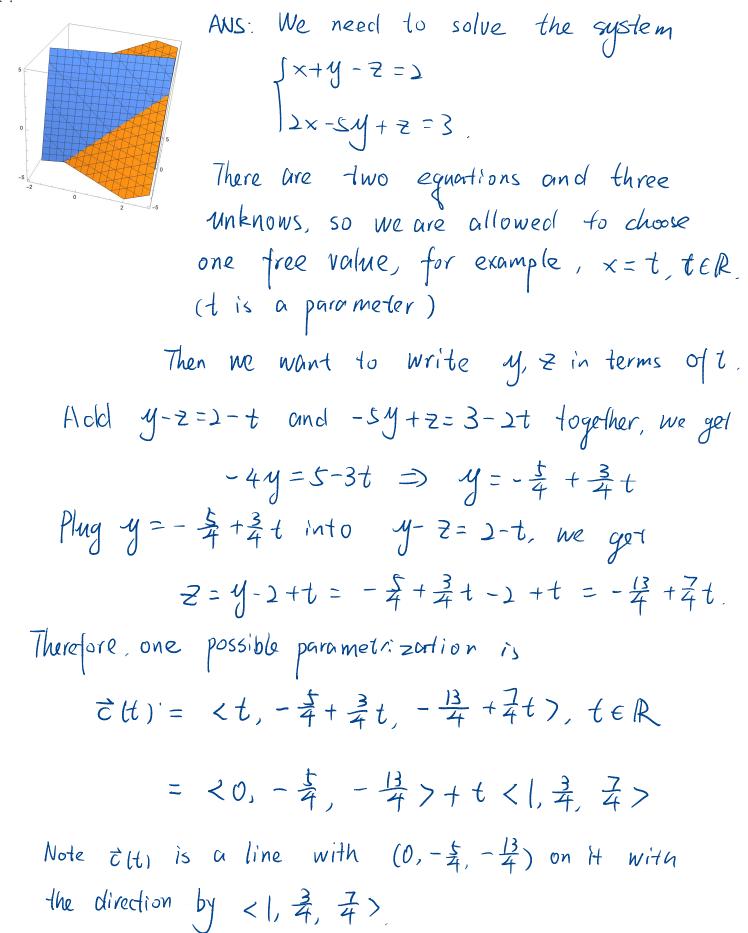
Then, one possible parametrization is

 $\vec{c}(t) = (\cos t, \sin t, 1 - \cos t), t \in [0, 2\pi].$ 

**Example 2** Find parametric equations of the curves that are obtained by intersecting the cylinder  $x^2 + z^2 = 1$  with the sphere  $x^2 + y^2 + z^2 = 4$ .



**Exercise 3** Find a parametric equation of the intersection of the planes x + y - z = 2 and 2x - 5y + z = 3 in  $\mathbb{R}^3$ .



# Tangents, Velocity, and Acceleration

- The velocity of a differentiable path  $\mathbf{c}(t)$  in  $\mathbb{R}^2$  or  $\mathbb{R}^3$  is given by  $\mathbf{v}(t) = \mathbf{c}'(t)$ , and its speed by the scalar function  $\|\mathbf{v}(t)\|$ .
- If  $\mathbf{c}(t)$  is twice differentiable, we define the acceleration by  $\mathbf{a}(t) = \mathbf{v}'(t) = \mathbf{c}''(t)$ .

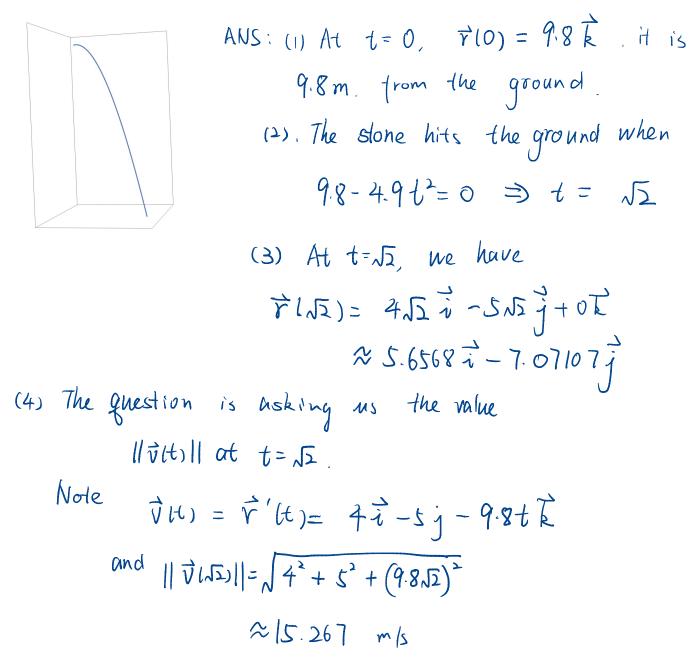
**Example 4.** The curve  $\mathbf{c}(t) = (e^{-t} \cos t, e^{-t} \sin t), 0 \le t \le 3\pi$ , represents the trajectory of a particle moving in  $\mathbb{R}^2$ . Compute its velocity and find all points at which the velocity is horizontal or vertical.

ANS: The velocity is  
ANS: The velocity is  

$$\vec{v}(t) = \vec{c}'(t) = (-e^{-t}\cos t - e^{-t}\sin t, -e^{-t}\sin t + e^{-t}\cos t)$$
  
 $= -e^{-t}(\cos t + \sin t, \sin t - \cos t)$   
The velocity is horizontal when its y coordinate is 0.  
that is sint - cost = 0  
 $\Rightarrow$  sint = cost  $\Rightarrow$  tant = 1.  
 $e^{-\pi}$   
 $e^{-\pi}$  Thus  $t = \mp, \mp, \frac{9\pi}{4}, \frac{9\pi}{4}$   
Thus  $t = \mp, \mp, \frac{9\pi}{4}, \frac{9\pi}{4}$   
 $= -e^{-\pi}(\frac{\pi}{5}, \frac{\pi}{5}), \vec{c}(\frac{5\pi}{4}) = -e^{-\frac{\pi}{4}}(\frac{\pi}{5}, \frac{\pi}{5})$   
 $\vec{c}(\frac{9\pi}{4}) = e^{-\frac{\pi}{4}}(\frac{\pi}{5}, \frac{\pi}{5}), \vec{c}(\frac{5\pi}{4}) = -e^{-\frac{\pi}{4}}(\frac{\pi}{5}, \frac{\pi}{5})$   
Similarly, we set x coordinate to be zero to  
find t such that the velocity is vertical.  
that is give = -\cos t,  $\Rightarrow$  tant = -1  
So we have  $t = \frac{3\pi}{4}, \frac{\pi}{4}, \frac{11\pi}{4}$   
Thus the vebcity is vertical of positions  
 $\vec{c}(\frac{3\pi}{4}) = e^{-\frac{\pi}{4}}(\frac{\pi}{5}, \frac{\pi}{5}), \vec{c}(\frac{\pi}{4}) = -e^{\frac{\pi}{4}}(\frac{\pi}{5}, \frac{\pi}{5})$   
 $\vec{c}(\frac{9\pi}{4}) = e^{-\frac{\pi}{4}}(\frac{\pi}{5}, \frac{\pi}{5}), \vec{c}(\frac{\pi}{4}) = -e^{\frac{\pi}{4}}(\frac{\pi}{5}, \frac{\pi}{5})$ 

**Example 5.** A stone is thrown from a rooftop at time t = 0 seconds. Its position at time t is given by  $\mathbf{r}(t) = 4t\mathbf{i} - 5t\mathbf{j} + (9.8 - 4.9t^2)\mathbf{k}$ . The origin is at the base of the building, which is standing on flat ground. Distance is measured in meters. The vector  $\mathbf{i}$  points east,  $\mathbf{j}$  points north, and  $\mathbf{k}$  points up.

- (1) How high is the rooftop?
- (2) When does the stone hit the ground?
- (3) Where does the stone hit the ground?
- (4) How fast is the stone moving when it hits the ground?



# Example 6.

(1) Compute the starting and ending positions (at times t = 0 and t = 1, respectively) for the path of motion described by the vector-valued function:  $\mathbf{h}(t) = \left(\sin(t), \frac{4t-5}{3t+4}, \cos(t)\right)$ .

(2) Compute the derivative of  ${f h}(t).$ 

(3) Compute the starting and ending velocities for  $\mathbf{h}(t)$ .

ANS: (1) The starting position  

$$\vec{h}(0) = \{0, -1.25, 1\}$$
  
The ending position is  
 $\vec{h}(1) = (0.841471, -0.141857, 0.540302)$   
(2)  $h(t) = (cost, \frac{4(3t+4)-3(4t-5)}{(3t+4)^2}, -sint)$   
 $h'(0) = (1, 1.9375, 0)$ 

h(1) = (0.540302, 0.632653, -0.841471)

**Exercise 7.** Let  $\mathbf{r}(t) = \langle t^2, 1 - t, 4t \rangle$ . Calculate the derivative of  $\mathbf{r}(t) \cdot \mathbf{a}(t)$  at t = 6, assuming that  $\mathbf{a}(6) = \langle 3, 7, -3 \rangle$  and  $\mathbf{a}'(6) = \langle -7, -5, -6 \rangle$ .

Solution: By the Product Rule for dot products we have

$$rac{d}{dt} \mathbf{r}(t) \cdot \mathbf{a}(t) = \mathbf{r}(t) \cdot \mathbf{a}'(t) + \mathbf{r}'(t) \cdot \mathbf{a}(t)$$

At t=6 we have

$$\left. \frac{d}{dt} \mathbf{r}(t) \cdot \mathbf{a}(t) \right|_{t=6} = \mathbf{r}(6) \cdot \mathbf{a}'(6) + \mathbf{r}'(6) \cdot \mathbf{a}(6)$$

We compute the derivative  $\mathbf{r}'(6)$  :

$$\mathbf{r}'(t) = rac{d}{dt} \langle t^2, 1-t, 4t 
angle = \langle 2t, -1, 4 
angle \Rightarrow \mathbf{r}'(6) = \langle 12, -1, 4 
angle$$

Also,  $\mathbf{r}(6)=\left\langle 6^2,1-6,4\cdot 6
ight
angle =\left\langle 36,-5,24
ight
angle .$ 

Substituting the vectors in the equation above, we obtain:

$$egin{aligned} & rac{d}{dt} \mathbf{r}(t) \cdot \mathbf{a}(t) \Big|_{t=6} = \langle 36, -5, 24 
angle \cdot \langle -7, -5, -6 
angle + \langle 12, -1, 4 
angle \cdot \langle 3, 7, -3 
angle \ &= (-252 + 25 - 144) + (36 - 7 - 12) = -354 \end{aligned}$$

The derivative of  $\mathbf{r}(t) \cdot \mathbf{a}(t)$  at t = 6 is -354 .